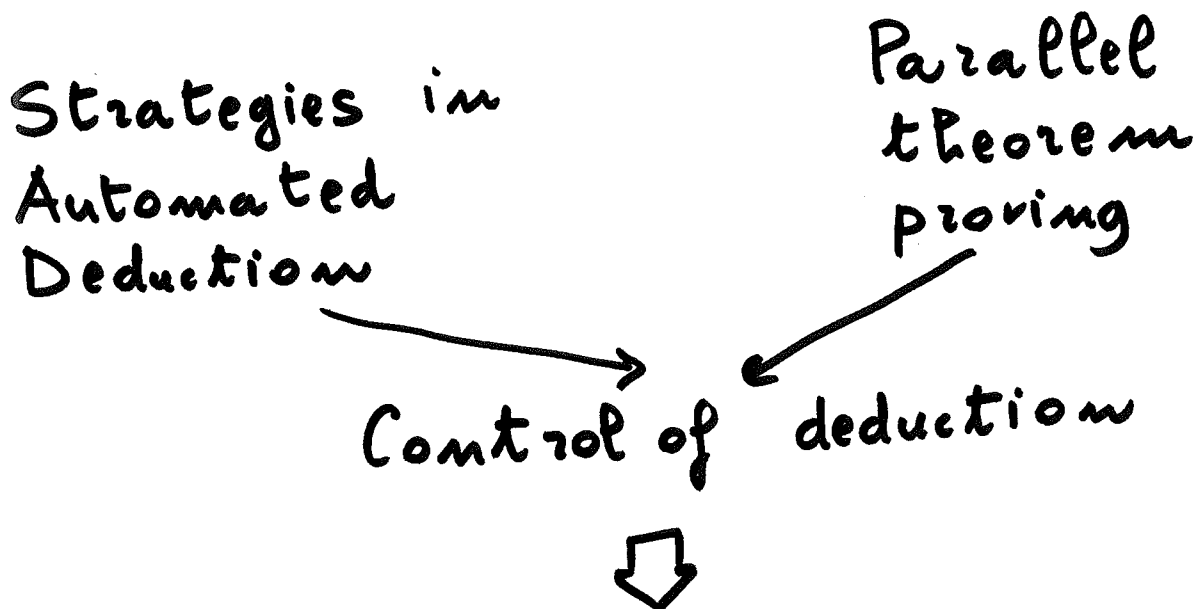


Ten years of
parallel theorem proving:
a perspective

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Motivation

Ten years of parallel theorem proving: 1989 - 1999



A taxonomy of parallel strategies based on how they search

Relevant to:

Analysis of strategies

Engineering of theorem provers

Outline

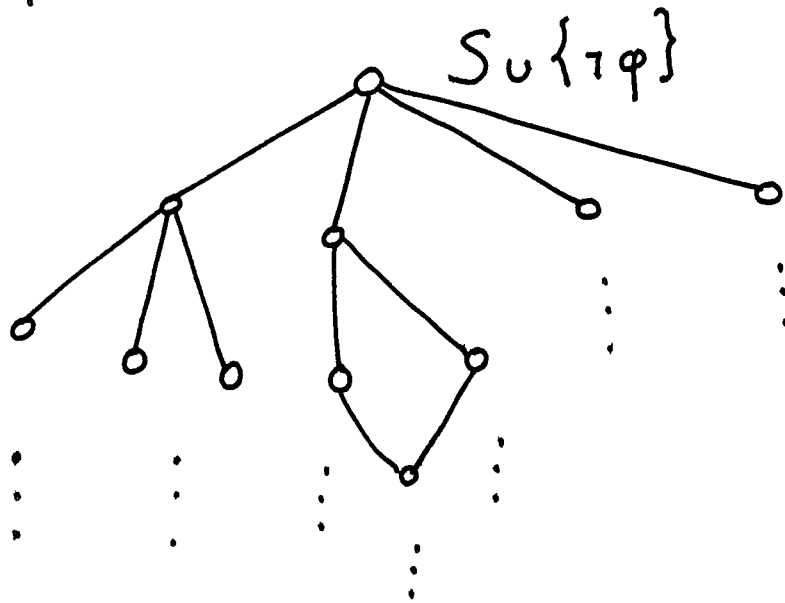
- A taxonomy of sequential theorem proving strategies
- Principles of parallelization
- How they affect the control of search and vice versa:
a taxonomy of parallel theorem proving strategies
- Parallel search plans
- Discussion: trends and open problems

A taxonomy
of
sequential strategies

Theorem proving as search problem

Inference system I

$$S \cup \{\neg\varphi\} \stackrel{?}{\vdash}_I \perp$$



vertex : state

arc : inference

path : derivation

Search plan Σ : determines unique derivation

Refutationally complete I

Fair Σ



theorem-proving strategy

$$\mathcal{P} = \langle I, \Sigma \rangle$$

complete

General scheme of search plan

$$\Sigma = \langle \zeta, \xi, \omega \rangle$$

(at least)

- rule-selecting function

$$\zeta : \text{States}^* \rightarrow I$$

- premise-selecting function

$$\xi : \text{States}^* \rightarrow \mathcal{P}(L_{\oplus})$$

- termination-detecting function

$$\omega : \text{States} \rightarrow \text{Bool}$$

Two main classes of strategies

Ordering-based strategies

work on a set of objects (state)

build many proof attempts implicitly

no backtracking

contraction

Subgoal-reduction strategies

work on one goal-object at a time (state)

build one proof attempt at a time

backtracking

no contraction

Ordering-based strategies

Resolution
+
paramodulation

Term rewriting
+
Knuth-Bendix

ordering
based
strategies

```
graph TD; A[Resolution + paramodulation] --> C[ordering based strategies]; B[Term rewriting + Knuth-Bendix] --> C;
```

E.g.,

Otter, RRL, Reveal, SNARK,
EQP, Barcelona, CLING-S, SPASS,
Gandalf, OSHL, daTac ...

Ordering based strategies

> : well-founded ordering on data

Expansion: $f: \frac{S}{S'}$ $S \subset S'$ $S < S'$

e.g.,

resolution, hyperresolution, paramodulation,
superposition

Contraction: $f: \frac{S}{S'}$ $S \not\subset S'$ $S > S'$

e.g.,

simplification, subsumption, taut. deletion,
purity deletion, clausal simplification

Redundancy

Ordered inference rules

Critical pair criteria

"Basic" inference rules

Ordering based strategies

$$\Sigma = \langle \gamma, \xi_1, \xi_2, \omega \rangle$$

$$\bullet \xi_1: \text{States}^* \longrightarrow \mathcal{L}_{\oplus}$$

$$\xi_1(S_0 \dots S_i) = \psi_1 \in S_i$$

$$\bullet \gamma: \text{States}^* \times \mathcal{L}_{\oplus} \longrightarrow I$$

$$\gamma(S_0 \dots S_i, \psi_1) = f$$

$$\bullet \xi_2: \text{States}^* \times \mathcal{L}_{\oplus} \times I \longrightarrow \mathcal{P}(\mathcal{L}_{\oplus})$$

$$\xi_2(S_0 \dots S_i, \psi_1, f) = \{ \psi_2 \dots \psi_m \} \subseteq S_i$$

search plans of Otter and EQP

indexing

forward / backward contraction

$$S_0 \vdash S_1 \vdash \dots \vdash S_i \vdash S_{i+1} \vdash \dots$$

Expansion - oriented

$(S_0; N_0) \vdash (S_1; N_1) \vdash \dots (S_i; N_i) \vdash \dots$

$S_0 \subseteq S_1 \subseteq \dots S_i \subseteq S_{i+1} \subseteq \dots$

forward contraction

Contraction - based

$S_0 \vdash S_1 \vdash \dots S_i \vdash S_{i+1} \vdash \dots$

$R(S_0) \subseteq R(S_1) \subseteq \dots R(S_i) \subseteq R(S_{i+1}) \subseteq \dots$

eager forward and backward contraction

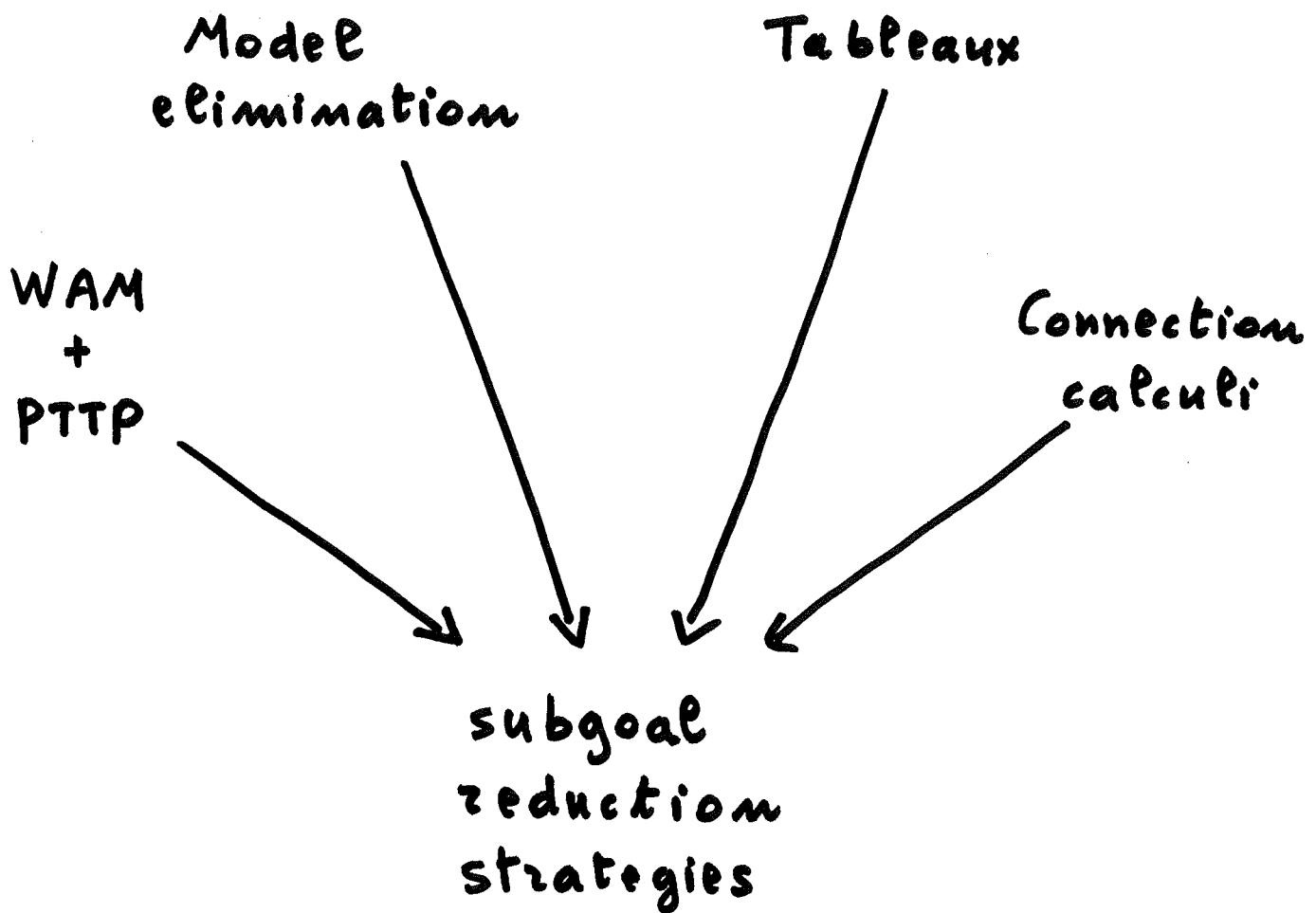
Target - oriented

$(S_0; \varphi_0) \vdash (S_1; \varphi_1) \vdash \dots (S_i; \varphi_i) \vdash \dots$

Semantic / Supported

$(T_0; SOS_0) \vdash (T_1; SOS_1) \vdash \dots (T_i; SOS_i) \vdash \dots$

Subgoal-reduction strategies



E.g. :

Setko, METEOR, Protein, TAP,

TatzeWuzm, Mission, KOMET ...

Subgoal reduction strategies

$$\Sigma = \langle \gamma, \xi_1, \xi_2, \omega \rangle$$

- $\xi_1 : \text{States}^* \longrightarrow \mathcal{L}_{\text{H}}$
 $\xi_1((T_0; X_0) \dots (T_i; X_i)) = L \in \text{open}(X_i)$
- $\gamma : \text{States}^* \times \mathcal{L}_{\text{H}} \longrightarrow I \cup \{\text{backtrack}\}$
- $\xi_2 : \text{States}^* \times \mathcal{L}_{\text{H}} \times I \longrightarrow \mathcal{L}_{\text{H}}$
 $\xi_2((T_0; X_0) \dots (T_i; X_i), L, f) = \psi \in T_i$

$\xi_1 \approx$ AND-computation rule

$\xi_2 \approx$ OR-computation rule

$$(T_0; X_0) \vdash (T_1; X_1) \vdash \dots (T_i; X_i) \vdash \dots$$

Analytic - tableaux

$$\chi_0 \vdash \chi_1 \vdash \dots \chi_i \vdash \dots$$

Linear clausal

$$(T_0; \varphi_0; A_0) \vdash \dots (T_i; \varphi_i; A_i) \vdash \dots$$

Linear - input clausal

$$(T_0; \varphi_0) \vdash \dots (T_i; \varphi_i) \vdash \dots$$

ME - tableaux

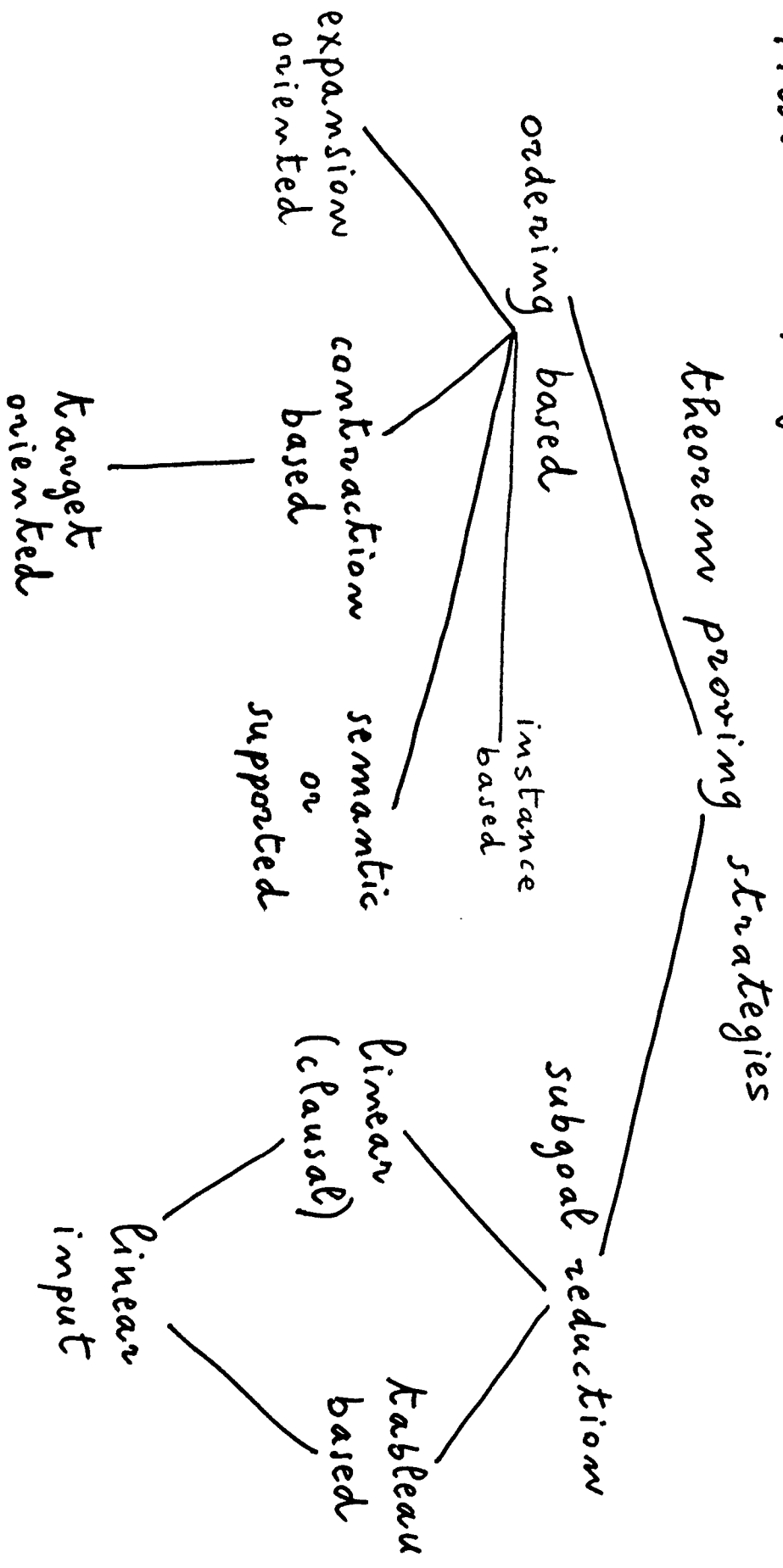
$$(T_0; \chi_0) \vdash \dots (T_i; \chi_i) \vdash \dots$$

Term rewriting

$$(T_0; \varphi_0) \vdash \dots (T_i; \varphi_i) \vdash \dots$$

A Taxonomy of strategies

First order, general purpose, fully automated



Principles of parallelization

PARALLELISM	DATA ACCESSED IN PARALLEL	PARALLEL OPERATIONS
AT THE TERM LEVEL	Subexpressions of formulae	Subtasks of inferences
AT THE CLAUSE LEVEL	formulae	inferences
AT THE SEARCH LEVEL	sets of formulae	derivations

Principles of parallelization

Parallelism at the term level:

parallel inner algorithms
below the inference level
speed-up frequent operations

Parallelism at the clause level:

parallel inferences
speed-up the given search

Parallelism at the search level:

generate many different searches
in parallel \Rightarrow parallel
derivations

Parallel search

How differentiate / combine the parallel search processes?

Distributed search:

subdivide the search space

decompose the problem

motivation: divide work

Multi-search:

whole problem to each process

different search plans

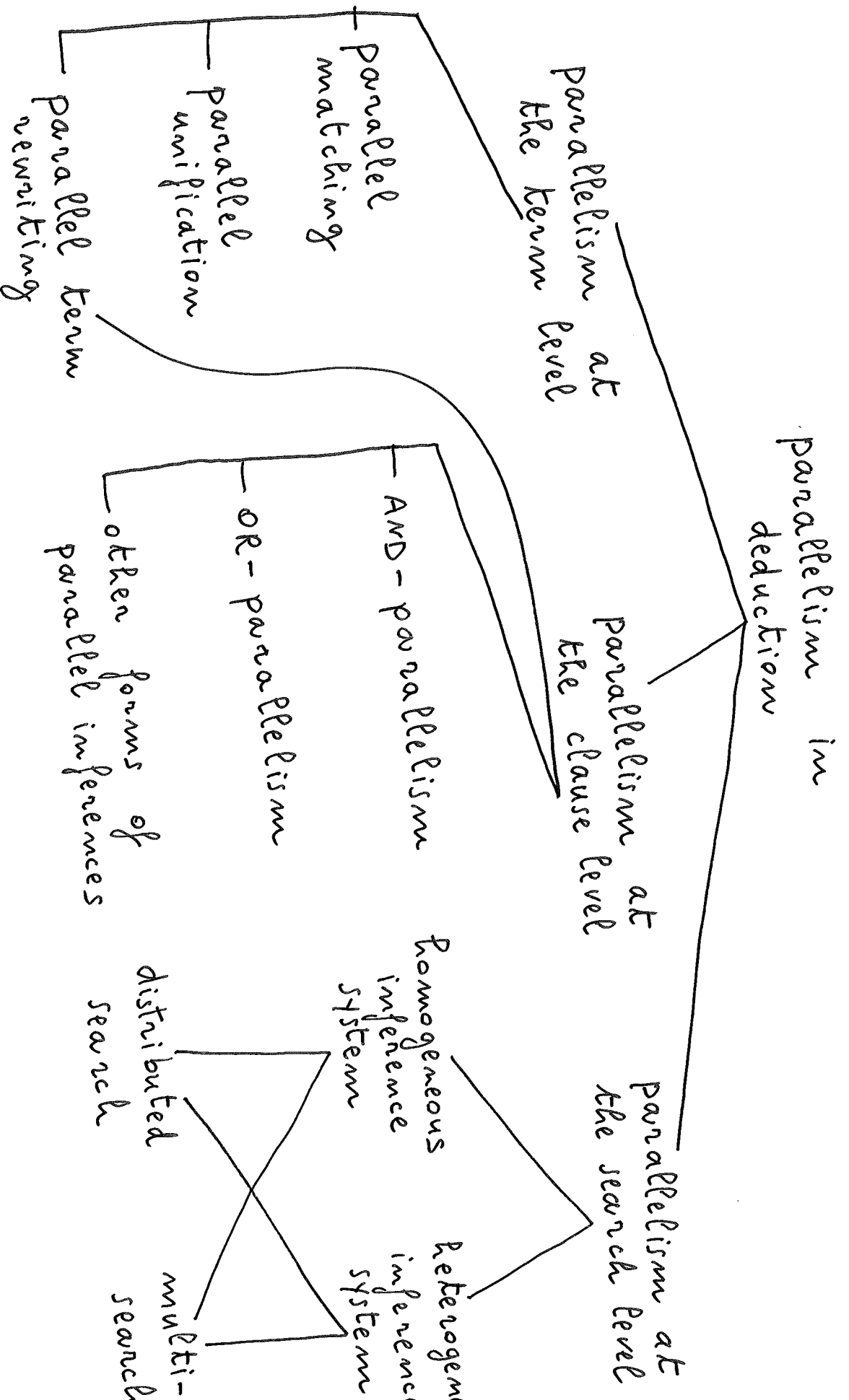
motivation: different orders

Heterogeneous systems:

different inference systems

motivation: combine backward and

forward reasoning, e.g., Lemmas



A taxonomy of
parallel

theorem proving
strategies

Sequential

$$\mathcal{C} = \langle I, \Sigma \rangle$$

Parallel

$$\mathcal{C}' = \langle I, \Sigma' \rangle$$

What is Σ' ?

The search plan and parallelism at the term level

- Concurrent rewriting
[Kirchner - Vity 1990,
Alouini 1995,
Alouini - Kirchner 1996]
- Concurrent completion
[Kirchner - Lynch - Scharff 1996]
- "Concurrent theorem proving"
[Fisher 1997]
- Pa Re Du X
[Bündgen - Göbel - Küchlin
1994 - 1995 - 1996]

Example concurrent rewriting

$$\Sigma = \langle \xi, \omega \rangle$$

$$\Sigma' = \langle \xi', \omega \rangle$$

Terms as trees: disjoint redexes

Terms as dags: non-overlapping redexes



(maximal) concurrent rewriting

Data structure dictates what is done in parallel:

Σ' superfluous

Data-driven concurrency

Also:

conditional rewriting

ground completion

unit resolution for Horn
propositional clauses

Non-ground inferences?

"Strategy-compliant"

parallelization : guarantees

same order of steps

The search plan and parallelism at the term level

Parallelism is introduced below the level where the search plan makes decisions

Possibilities:

1) Concurrency replaces the search plan
(e.g., concurrent rewriting)

2) "Strategy-compliant" parallelization (e.g., PaReDuX):

$$\Sigma' = \Sigma$$

$$\mathcal{E}' = \mathcal{E}$$

The search plan and parallelism at the clause level

ORDERING - BASED

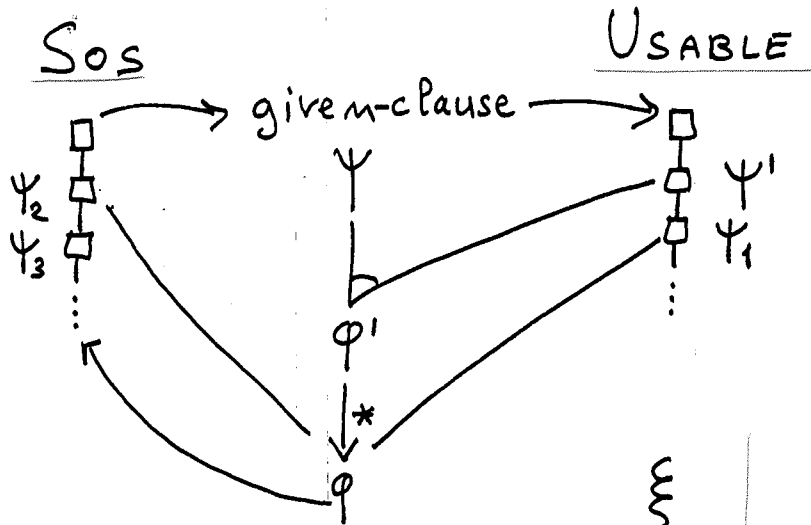
- Expansion-oriented
PARROT [Jindal-Overbeek-Kabat 1992]
- Instance-based
Parallel Hyper-linking [Lee-Wu 1997]
- Contraction-based
ROO [Lusk-McCune 1990]
Transition-based parallel completion
[Yelick-Garland 1992]

SUBGOAL-REDUCTION

- PTTP (clausal linear-input)
PARTHENON [Bose-Clarke-Long-Mychalov 1989]
METEOR [Astrachan-Loveland 1991]
- ME-tableaux (linear-input)
PARTHEO [Schumann-Letz 1990]
- Analytic tableaux
HOT [Konrad 1998]
- Gentzen-style subproofs in NUPRL
[Hickey 1999]

Example: ROO parallelization of Otter

$\Sigma = \langle \mathcal{S}, \mathcal{S}_1, \mathcal{S}_2, \omega \rangle$: given-clause algorithm



Expansion
 Forward contraction
 Backward contraction

\mathcal{S}_1	\mathcal{S}	\mathcal{S}_2
Ψ	exp. rule	Ψ'
Ψ'	contr. rule	Ψ_1, Ψ_2
Φ	contr. rule	Ψ_3

$\Sigma' = \langle \mathcal{S}, \mathcal{S}'_1, \mathcal{S}'_2, \omega \rangle$: shared S0S and USABLE

Each process does a given-clause (Task A)

Problems: concurrent append / redundant insertions/
 concurrent deletion

Add lists K-LIST and TO-BE-DELETED : Task B

At most one process does Task B

(Problem: backward contraction bottleneck)

⇒ Parallel plan as task scheduler

Parallel plan as task scheduler

Also:

PTTP with OR-parallelism
(e.g., PARTHENON, METEOR)

ME-tableaux with OR-parallelism
(e.g., PARTHEO)

Analytic tableaux
(e.g., HOT)

Gentzen-style proofs
(e.g., in NUPRL)

Common traits:

Shared data structure:

stack of goals, blackboard ...

Tasks: subgoals, open leaves ..

Control: task scheduling
(e.g., task stealing)

The search plan and parallelism at the clause level

Parallelism is introduced at the level where the search plan makes decisions.

Sequential search plan: order the inferences within one derivation.

Parallelism at the clause level:

parallelize the inferences within derivation.



Parallel search plan: scheduler assigning inferences to processes.

The search plan and parallelism at the search level

Each process generates a derivation



Each process needs to execute a search plan

Such search plan needs to control:

- inferences (like sequential)
- subdivision of work (distributed search)
- communication (both distributed and multi-search)

for: completeness
cooperation
load-balance

Two approaches:

- hierarchy of processes (e.g., master-slaves)
- peer processes

The search plan and parallelism at the search level

Parallel search with master-slaves:

- Multi-search:
Team-Work (contraction-based)
[Avenhaus - Demzinger - Fuchs - Kronenburg -
Schulz 1993, 1994, 1995, 1996]
- Distributed search:
PSATO (satisfiability)
[Zhang - Bonacina - Hsiang 1994, 1996]
- Heterogeneous systems:
HPDS (subgoal reduction + expansion oriented)
[Sutcliffe 1992]
Distributed Larch Prover (contraction-based)
[Vandevorde - Kapur 1996]
- Multi-search + "AND-parallelism":
"Nagging" (subgoal-reduction : PTP)
[Sturgill - Segre 1994, 1997]

The search plan and parallelism at the search level

Parallel search with master slaves:

- separate the control of parallelism and the control of deduction;
- each slave executes a sequential search plan to generate its derivation;
- all other control issues (subdivision, communication, selection of data for cooperation, user interface) are dealt with by the master which does not do deductions;

$$\Sigma' = \langle \Sigma_1, \Sigma_2, \dots, \Sigma_n \rangle$$

The search plan and parallelism at the search level

Parallel search with peer processes:

- Distributed search:

DARES (expansion-oriented)

[Comry - MacIntosh - Meyer 1990]

Clause-Diffusion (contraction-based)

[Bonacina, Bonacina-Hsiang 1992, 1993, 1995]

[Bonacina - McCune 1994]

Modified Clause-Diffusion

[Bonacina 1994, 1996, 1997]

- Heterogeneous systems
(combinations of provers):

SPASS // DISCOUNT (contraction-based)

[Fuchs 1998]

CPTHEO = SETHEO // DELTA (subgoal-reduction +
[Fuchs - Wolff - Letz 1998] expansion-oriented)

The search plan and parallelism at the search level

Parallel search with peer processes:

- no central control;
- the search plan executed by each peer process needs to take care of the control of parallelism (e.g., communication, subdivision) together with the control of deduction



parallel-search plans

Search plan with communication

A set I of inference rules

$$f: \mathcal{P}(L_H) \longrightarrow \mathcal{P}(L_H) \times \mathcal{P}(L_H)$$

A set M of communication operators:

$$\text{send}: \mathcal{P}(L_H) \longrightarrow \mathcal{P}(L_H) \times \mathcal{P}(L_H)$$

$$\text{s.t. } \forall X \quad \text{send}(X) = (\phi, \phi)$$

$$\text{receive}: \mathcal{P}(L_H) \longrightarrow \mathcal{P}(L_H) \times \mathcal{P}(L_H)$$

$$\text{s.t. } \forall X \quad \text{receive}(X) = (X, \phi)$$

$$\Sigma = \langle \gamma, \xi, \omega \rangle$$

- $\gamma: \text{States}^* \times \mathbb{N} \times \mathbb{N} \longrightarrow I \cup M$
select rule/operator
- $\xi: \text{States}^* \times \mathbb{N} \times \mathbb{N} \times (I \cup M) \longrightarrow \mathcal{P}(L_H)$
select premises
e.g., $\xi(S_0 \dots S_i, m, k, f) \subseteq S_i$
- $\omega: \text{States} \longrightarrow \text{Bool}$
detect success

Parallel-search plans

Search plan for multi-search:

multi-plan

a collection of search plans with
communication one per process

$$\Sigma = \langle \Sigma_1 \dots \Sigma_n \rangle$$

Search plan for distributed search:

distributed-search plan

search plan with communication
+
subdivision function

$$\Sigma = \langle \mathcal{J}, \mathcal{F}, \alpha, \omega \rangle$$

Parallelizations

Search plan with communication

$$\Sigma' = \langle \zeta', \xi', \omega \rangle \text{ corresponds to}$$

sequential search plan

$$\Sigma = \langle \zeta, \xi, \omega \rangle \text{ if}$$

ζ' and ξ' select inferences like ζ and ξ
(difference is communication).

A multi-plan $\Sigma' = \langle \Sigma'_0 \dots \Sigma'_n \rangle$

is a parallelization by combination

of sequential search plans $\Sigma_0 \dots \Sigma_n$

if Σ'_i corresponds to Σ_i , $0 \leq i \leq n$.

A distributed-search plan

$$\Sigma' = \langle \zeta', \xi', \alpha, \omega \rangle$$

is a parallelization by subdivision

of sequential search plan $\Sigma = \langle \zeta, \xi, \omega \rangle$

if $\langle \zeta', \xi', \omega \rangle$ corresponds to Σ

(difference is also made by α).

Parallel strategies

in the sense of parallel search

Homogeneous parallel strategy $\langle I, M, \Sigma \rangle$

↙
multi-search strategy

if Σ is multi-plan

↘
distributed strategy

if Σ is distributed-search plan

Notions of parallelization by combination / subdivision extend to strategies assuming same I .

Heterogeneous parallel strategy

$\langle I_0 \dots I_{n-1}, \Sigma, M \rangle$

with same options for Σ .

General notion of parallel derivation which can be specialized to the various cases

parallelism in deduction

parallelism at the term level

parallelism at the clause level

parallelism at the search level

parallel matching
parallel unification
parallel rewriting

AND-parallelism
OR-parallelism
other forms of parallel inferences

homogeneous inference system
distributed search

heterogeneous inference system
multi-search

subgoal-reduction

expansion-oriented

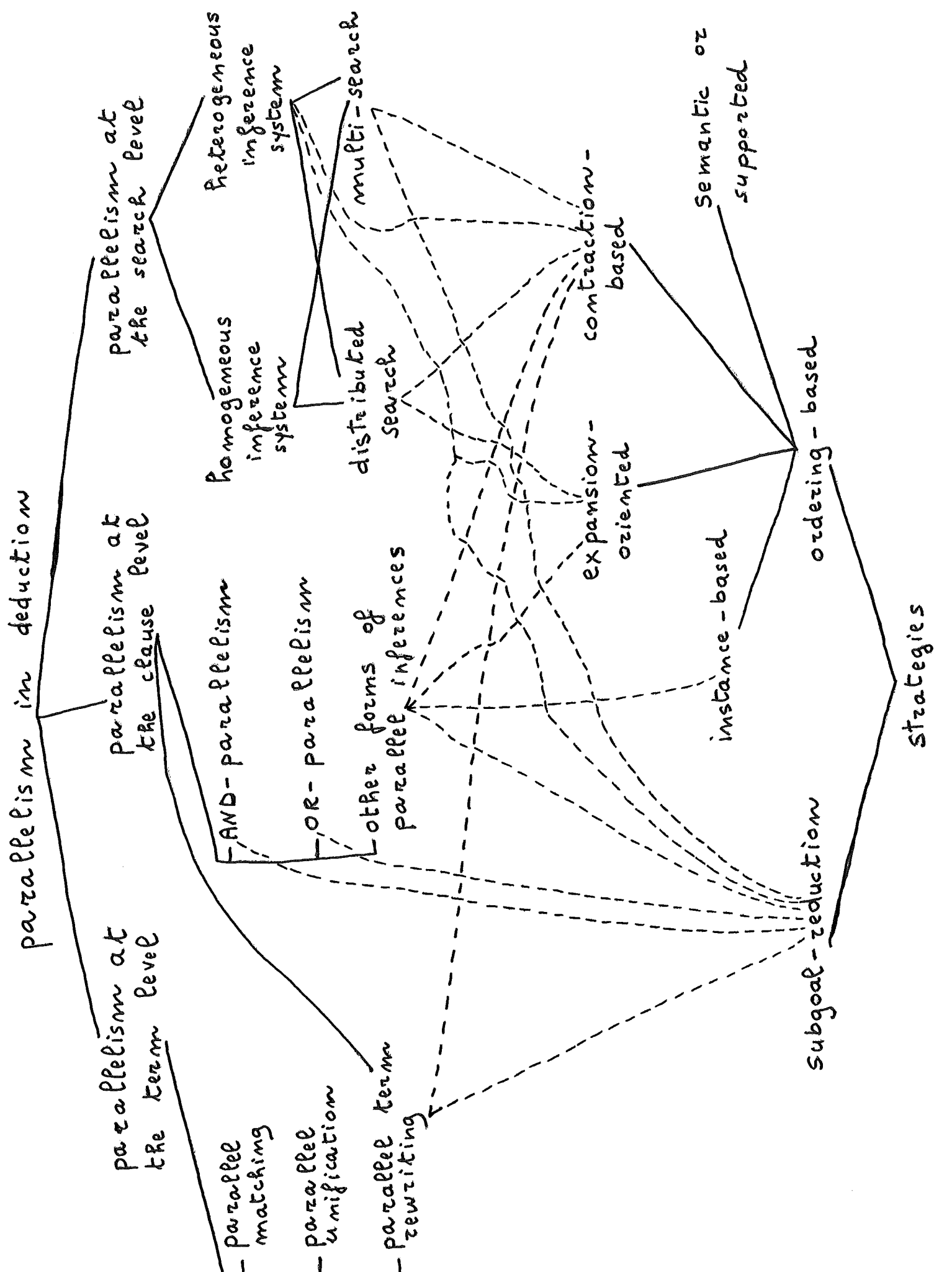
contraction-based

instance-based

semantic or supported

ordering-based

Strategies



First analysis

Size of data base

Dynamics of data base

Pre-processing

Read-only data

Special data structures

Conflicts: backward contraction
"backward-contraction bottleneck"



Parallelism at the search level

most suitable for theorem proving

especially contraction-based

[Bonacina & Hsiang; "Parallelization of deduction strategies: an analytical study"
Journal of Automated Reasoning Vol. 13 1994]

Analysis of control of search

Parallelism at the term level:

- Concurrency replaces search plan:
Loss of control?
- "Strategy-compliant":
excess of control?

Parallelism at the clause level:

- Search plan as scheduler:
tasks too small?
(e.g., given-clause, subgoal)

Evolution 1992 - 1999

Fine-grain → Coarse-grain
Medium-grain → Coarse-grain

Master-slaves → Peers

Examples:

PaReDuX → PaReDuX + TeamWork

PARTHEO → CPTHEO

HPDS → CPTHEO

Also:

Cause-Diffusion → Modified Cause-Diffusion

Team Work with master-slaves → Team Work with peers

Parallel search

- Cost of communication?
 - + ignore "redundant" data
 - delay \Rightarrow do redundant steps
- Overlapping searches?

Distributed search: dynamic heuristic subdivision

Multi-search: too similar plans
all fair, all exhaustive
scarcity of search plans

+ Early difference may suffice

- Scalability?

Distributed search: subdivision depends on # of processes also qualitatively

Multi-search / Heterogeneous: extra plan or rules may not help

Directions for further research

Design

Parallel semantic strategies?

Distributed search for
subgoal-reduction strategies?

Analysis

Subdivision vs. overlap

Eager contraction vs. communication
in

Distributed-search contraction-based
strategies

by applying

Bounded search spaces methodology

[Bonacina; Strategies '98, JELIA '98]

More formal analyses?